

Approximations and uncertainties in the in-medium similarity renormalization group

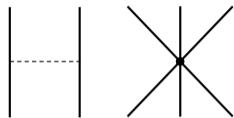
Matthias Heinz *with Jan Hoppe, Alexander Tichai, Kai Hebeler, and Achim Schwenk*

December 15, 2021

ISNET 8



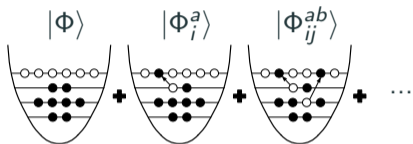
Ab initio many-body theory



$$H|\Psi\rangle = E|\Psi\rangle$$

Goal: Describe **many-body system** using only **few-body interactions** as input

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Exact diagonalization:

- Basis: Reference state $|\Phi\rangle$ and excitations

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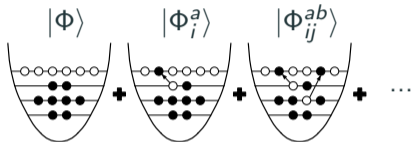
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Alternative expansion:

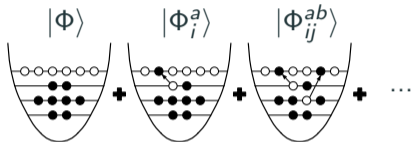
- Reference-state starting point: $E^{(0)}$
- Systematic construction of corrections



$$E = E^{(0)} + \begin{array}{c} E^{(2)} \\ \text{Diagram of two overlapping ellipses} \end{array} + \begin{array}{c} E^{(3)} \\ \text{Diagram of two overlapping ellipses with a central node} \end{array} + \dots$$

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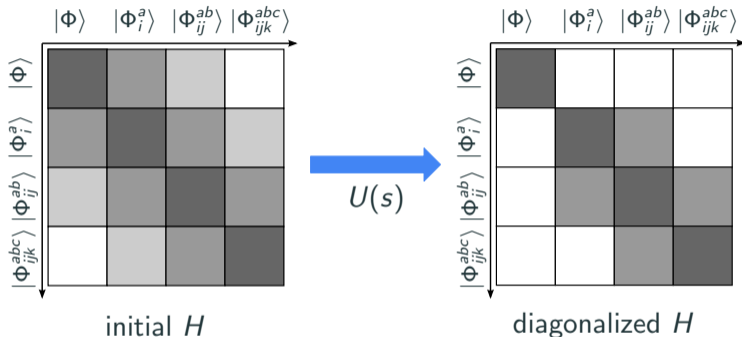
- Reference-state starting point: $E^{(0)}$
- Systematic construction of corrections
- What is error due to many-body truncation?

$$E = E^{(0)} + \begin{array}{c} E^{(2)} \\ \text{Diagram} \end{array} + \begin{array}{c} E^{(3)} \\ \text{Diagram} \end{array} + \dots$$

The diagram shows the energy expansion $E = E^{(0)} + E^{(2)} + E^{(3)} + \dots$. The $E^{(2)}$ term is represented by a diagram of two overlapping ellipses, and the $E^{(3)}$ term is represented by a diagram of two overlapping circles.

The in-medium similarity renormalization group

Tsukiya, Bogner, Schwenk, PRL **106** (2011)



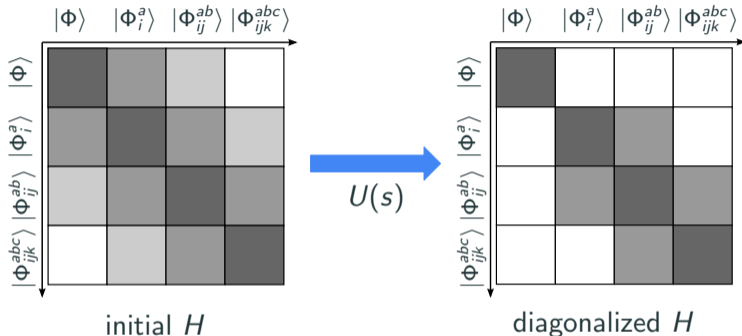
Hergert *et al.*, Phys. Rep. **621** (2016)

SRG flow equation:

$$\frac{dH(s)}{ds} = [\eta(s), H(s)]$$

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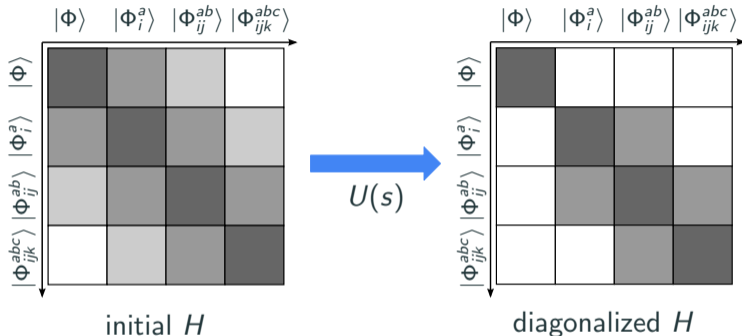
$$\frac{dH(s)}{ds} = [\eta(s), H(s)]$$

$$H(s) = E(s) + f(s) + \Gamma(s) + W(s) + \dots$$

$$\eta(s) = \eta^{(1)}(s) + \eta^{(2)}(s) + \eta^{(3)}(s) + \dots$$

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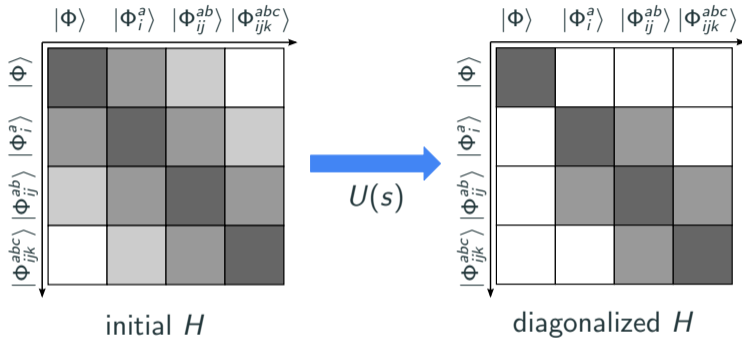
$$\frac{dH(s)}{ds} = [\eta(s), H(s)]$$

$$\text{IMSRG(2)} \quad H(s) = E(s) + f(s) + \Gamma(s) + W(s) + \dots$$

$$\eta(s) = \eta^{(1)}(s) + \eta^{(2)}(s) + \eta^{(3)}(s) + \dots$$

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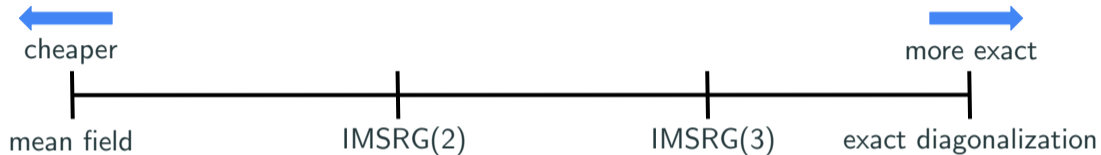
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IMSRG(2) $H(s) = E(s) + f(s) + \Gamma(s) + W(s) + \dots$

IMSRG(3) $\eta(s) = \eta^{(1)}(s) + \eta^{(2)}(s) + \eta^{(3)}(s) + \dots$

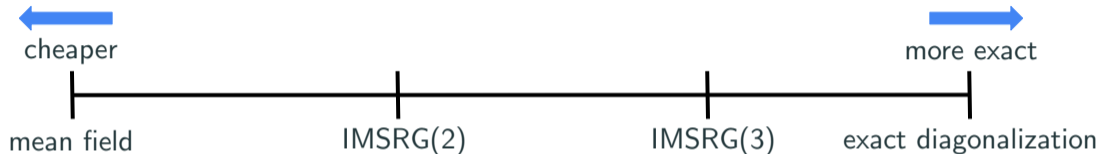
Investigating the many-body expansion

MH, Tichai, Hoppe, Hebeler, Schwenk, PRC **103** (2021)



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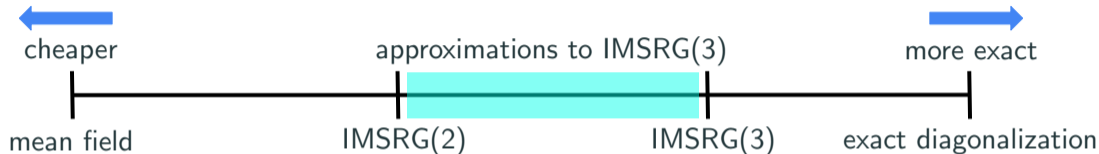
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- Systematic expansion to approximate exact result
- Ideal study: compare IMSRG(2) and IMSRG(3) to exact results
 - Only possible in small systems

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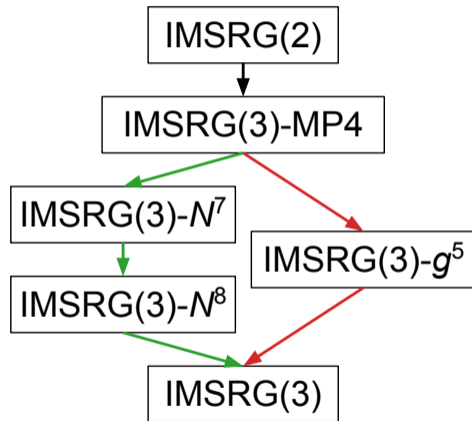
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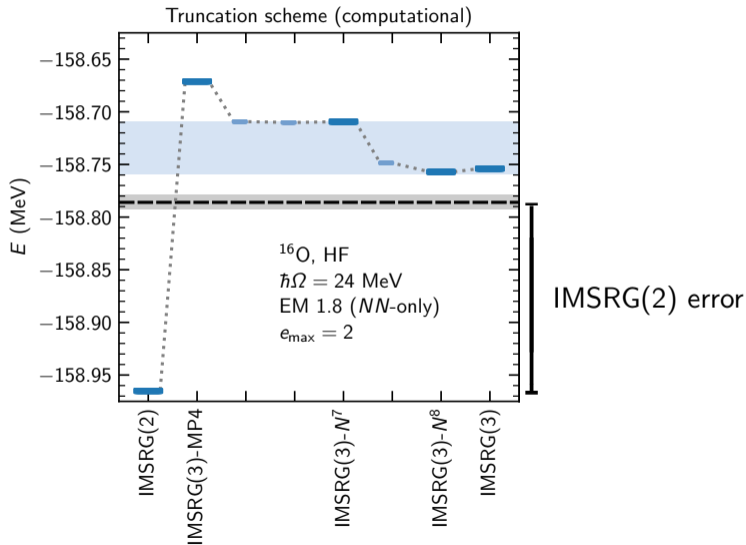
- Systematic expansion to approximate exact result
- Ideal study: compare IMSRG(2) and IMSRG(3) to exact results
 - Only possible in small systems
- Study truncations that approximate IMSRG(3) at lower computational cost

Going from IMSRG(2) to IMSRG(3)

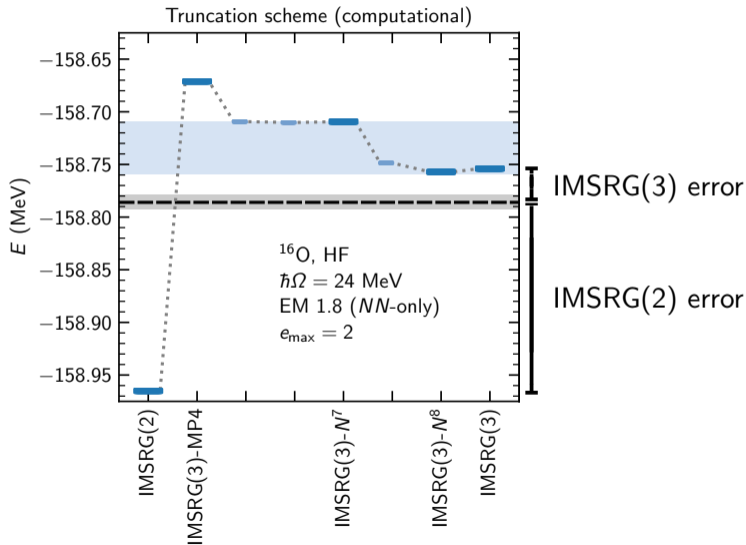
- 10 new terms in IMSRG(3)
- 4 included in IMSRG(3)-MP4 (minimal extension of IMSRG(2))
- Remaining terms can be categorized according to:
 - **Computational cost** ($\mathcal{O}(N^7)$ - $\mathcal{O}(N^9)$)
 - $\mathcal{O}(N^7) \sim 8$ minutes
 - $\mathcal{O}(N^9) \sim 14$ hours
 - **Perturbative importance** (g^5 , g^6)
 - MP4 contains all g^4 terms



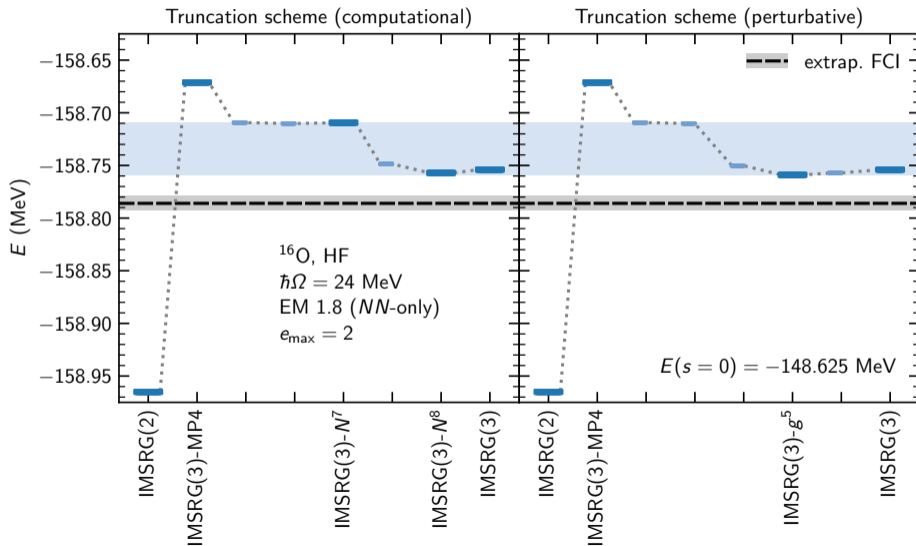
Application in oxygen-16



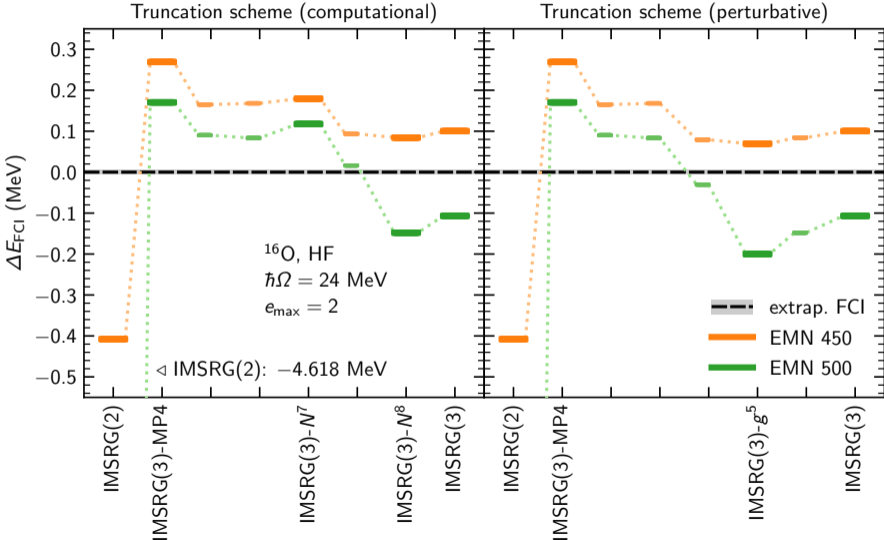
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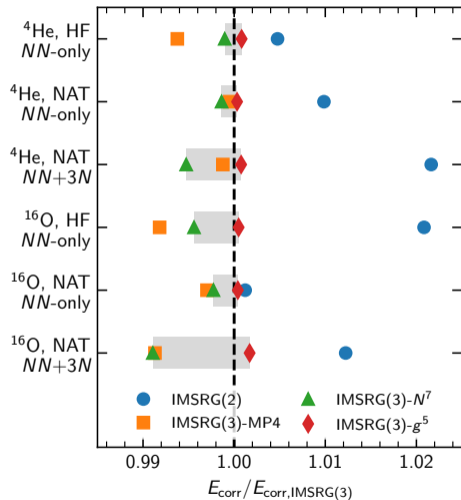
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Results for other Hamiltonians

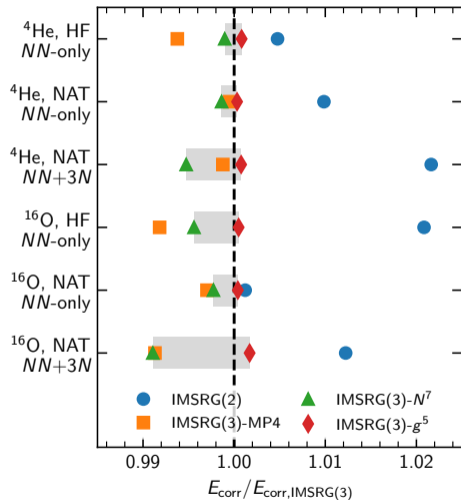


General trends for approximating the IMSRG(3)



- IMSRG(3) well approximated by:
 - IMSRG(3)- N^7 (lower cost)
 - IMSRG(3)- g^5 (higher cost)
- Use 2 different truncations to estimate IMSRG(3) approximation error:
 - Easy: IMSRG(2) and IMSRG(3)-MP4
 - Better: IMSRG(3)- N^7 and IMSRG(3)- g^5

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 - Easy: IMSRG(2) and IMSRG(3)-MP4
 - Better: IMSRG(3)- N^7 and IMSRG(3)- g^5
- IMSRG(3) approximation error is a *proxy* for many-body error

Key takeaways:

- IMSRG many-body expansion converges systematically
- IMSRG(3) convergence benefits can be approximated at lower computational cost
- Many-body UQ is possible!

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Next developments:

- Apply (approximate) IMSRG(3) to large-scale calculations of nuclei ...
- ... including other observables
- Accelerate IMSRG calculations to enable more expensive truncations:
 - Improved basis construction [Hoppe *et al.*, PRC **103** \(2021\)](#)
 - Importance truncation to discard unimportant (three-body) matrix elements [Hoppe *et al.*, arxiv:2110.09390 \(2021\)](#)
- Refine UQ for many-body calculations (emulators, model mixing, etc.)

Discussion points and acknowledgments

- How can we best leverage our sequentially refined models using Bayesian tools?
- What features of (extremely expensive) many-body calculations can be leveraged to develop improved emulators?

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- Jan Hoppe,
- Alexander Tichai,
- Kai Hebel,
- Achim Schwenk,
- and more at the TU Darmstadt and beyond.

Thank you for your attention!

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